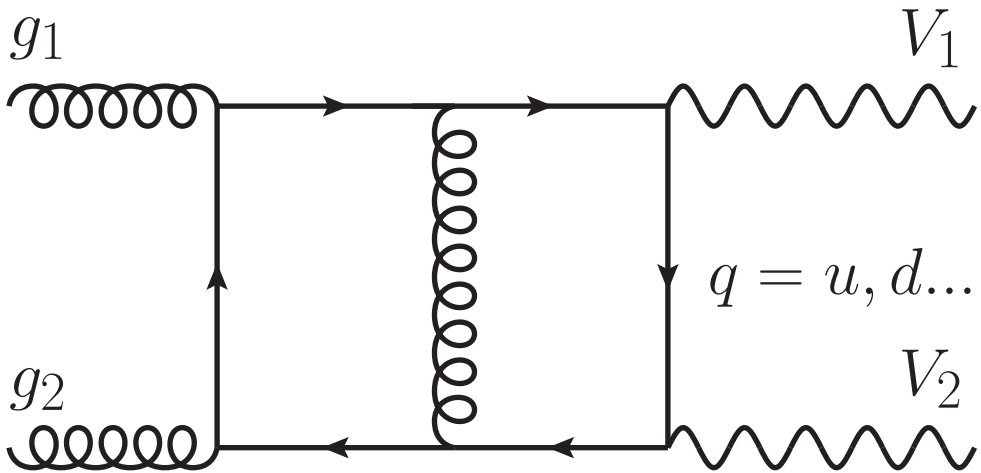
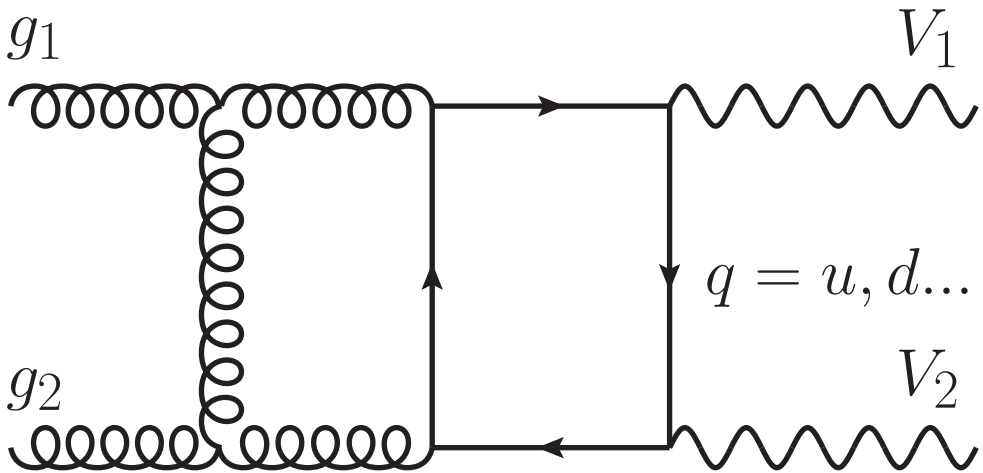

g_1
V_1
$q = u, d...$
g_2
V_2


g_1
V_1
$q = u, d...$
g_2
V_2